Bailey

SECTION
E12-42

PRODUCT INSTRUCTIONS

ELECTRIC RECEIVER FOR TYPE WM55 RECORDER AND TYPE WM53 INDICATOR (ASSEMBLY AND COMPONENTS)

INDEX

	Page
Cross References	2
Installation	4
Component Parts of the Receiver	5
Adjustment and Calibration	6
Maintenance	7
Motor Specifications	10
Accessories	11
Replacement Parts	12

One to four Electric Receivers may be mounted in a Type WM55 Recorder, or Type WM53 Indicator (maximum of two indicating in WM53). Each Receiver comprises the receiving portion of one electrical measuring or calculating circuit, and contains:

(1) a wiring board assembly;
(2) an amplifier, plugged into the wiring board;
(3) a motor driven slidewire disc and cam assembly, which positions a drive arm.

The drive arm may be used to operate recording, indicating, integrating, and control devices.

This Instruction Section covers Receiver parts and accessories that are standard for most circuit classes:

(1) Receiver Case
(2) Motor driven slidewire disc and cam
(3) Accessories
    (a) Retransmitting slidewire
    (b) Retransmitting movable core transformer
    (c) Alarm contacts

Refer to Cross References, page 2, for listing of Instruction Sections covering circuit variations of the Receivers, and the Type WM55 Recorder.

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FORM IE12-42-1267

CROSS REFERENCES

Instrument or Equipment	Instruction Section
Class B1 and B2 Telemeter Receivers (AC Voltage Balance Circuit)	E12-16
Class B3, B4, and B5 Flow Receivers (AC Voltage Balance Circuit)	E12-17
Class BL and BN Telemeter Receivers (AC Voltage Balance Circuit)	E12-73
Class E1 and E2 Telemeter Receivers (DC Potentiometer Circuit, Low Level)	E12-22
Class E3 and E4 Temperature Receivers (DC Potentiometer Circuit)	E51-32
Class E7 and E8 Telemeter Receivers (DC Potentiometer Circuit)	E12-24
Class EA and EB Telemeter Receivers (DC Potentiometer Circuit, Low Level)	E12-77
Class EF and EG Temperature Receivers (DC Potentiometer Circuit)	E12-78
Class G1 and G2 Smoke Density Receivers	E66-4
Class G3, G5, and G6 Gas Analysis Receivers	E65-12
Class G4 Gas Analysis Receiver (Factory Mutual Approved)	E65-13
Class G7 Temperature Receiver	E12-28
Class G8 Electric Receiver (For OD10 Gas Analyzer)	E65-4
Class G9 Temperature Receiver (For Type UR Radiation Bolometer)	E51-73
Class GC, GD, and GE Gas Analysis Receivers	E65-17
Class GF Gas Analysis Receiver	E65-18
Class GG Electric Receiver (For OD10 Gas Analyzer)	E65-14
Class GL and GN Smoke Density Receivers	E71-6
Class GR Temperature Receiver (For Type UR Radiation Bolometer)	E51-74
Class H1, H2, and H3 AC Potentiometer Receivers (Computer Functions)	E12-66
Class H4 Electric Receiver (For Magnetic Flow Meter)	E12-67
Class HA, HB, and HC Electric Receivers (Computer Functions)	E12-75
Class J1 and J2 Telemeter Receivers (AC Voltage Ratio Circuit)	E12-13
Class JL and JN Telemeter Receivers (AC Voltage Ratio Circuit)	E12-19
Class L1, L2, L3, L4, L5, and L6 Electrolytic Conductivity Receivers	E67-2
Class LA, LB, LC, LF, LG, and LH Electrolytic Conductivity Receivers	E64-1
Class QA, QB, and QC Temperature Receivers (AC Wheatstone Bridge)	E51-3
Class QN, QQ, and QW Temperature Receivers (AC Wheatstone Bridge)	E51-4
Class QD and QE Electric Receiver (AC Wheatstone Bridge)	E12-26
Class QF and QV Temperature Receiver (AC Wheatstone Bridge)	E12-76
Class TA Program Controller	E99-71
Class TB Running Time Recorder	E26-2
Class W1 and W2 Electric Retransmitter (AC Output)	E99-81
Class W5, W6, and W7 Electric Retransmitter (DC Output)	E12-6

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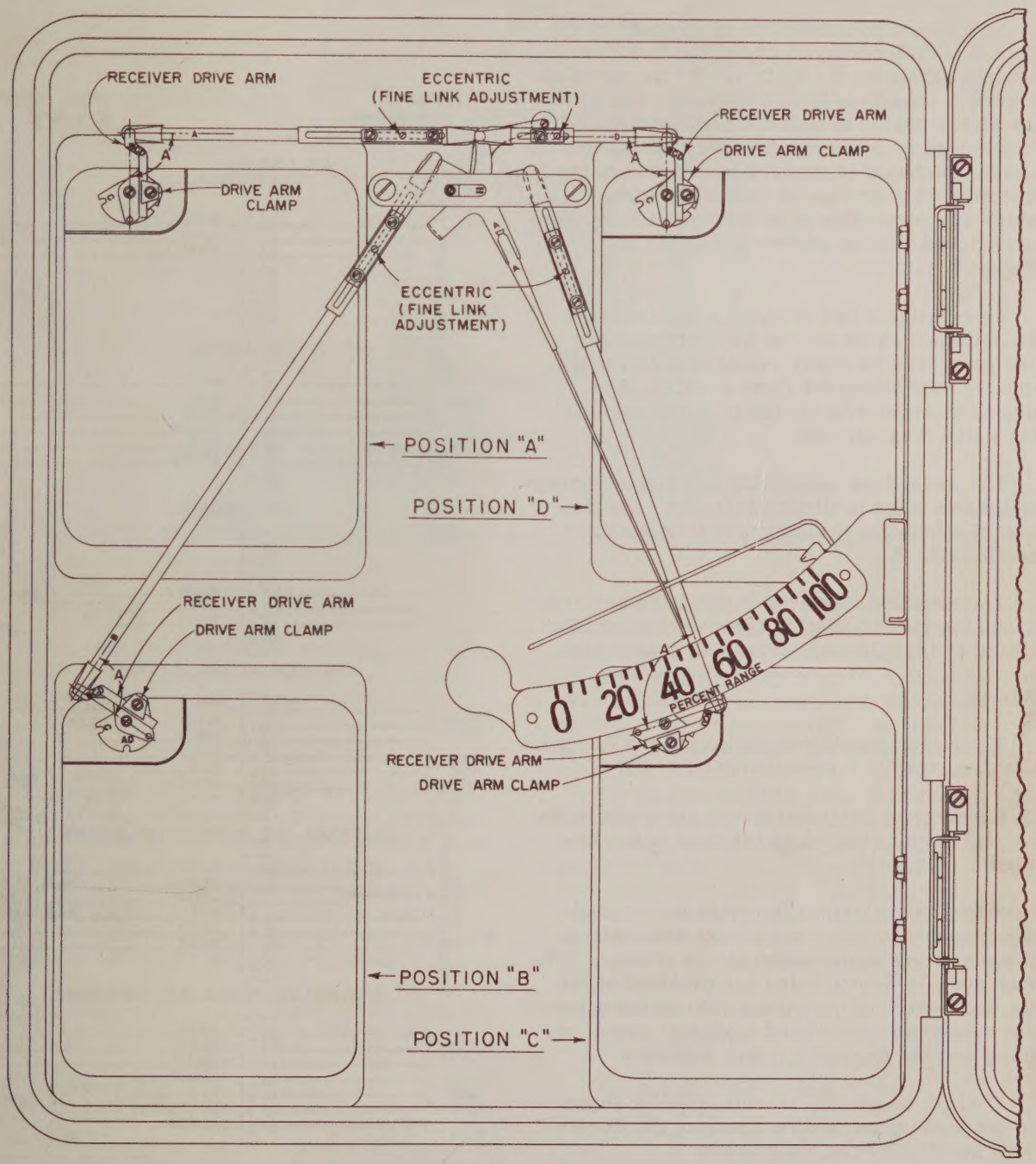


FIGURE 1 - Type WM55 Recorder with Four Electric Receivers

INSTALLATION

An Electric Receiver can be mounted in the Type WM55 Recorder in any of the four component positions - A, B, C, or D - as shown in Figure 1. In a Type WM53 Indicator, indicating Receivers can be mounted in positions A and B; Integrators or retransmitting auxiliaries in C and D. Each unit is secured to the rear of the Recorder by four captive mounting screws, which are accessible when the amplifier cover is removed. These screws are shown in Figure 3.

An adjustable link transmits the motion of the Receiver drive arm to its corresponding pen yoke. The Receiver requires a different link for each Recorder Case position. Each link is stamped with the letter of the position for which it is intended.

The method for connecting and disconnecting adjustable links is illustrated under "Installation of Additional Components" in Instruction Section E12-3.

To install the Receiver in the Recorder refer to the Instruction Section covering the specific Receiver (see Cross References on page 2).

Wiring

The power supply connections to the Recorder are described in Instruction Section E12-3

Connections to the Receivers are made in the central wiring channel on the rear of the Recorder (Figure 3).

Note that the polarized Receiver power plugs are inserted in the power socket assembly in the center of the Recorder wiring channel. 7/8-inch and 1-1/8-inch holes are provided at the top and bottom of the wiring channel for external measuring circuit and auxiliary circuit cables, and the Recorder power supply.

Connect measuring circuit leads as shown in the Instruction Section covering the Receiver's specific circuit application.

If the Receiver is equipped with accessories, such as alarm contacts, retransmitting slidewire, or retransmitting movable core transformer, make external connections to the auxiliary circuit terminals as shown in Figure 2. (This illustration does not apply to Class G Receivers for Factory Mutual Approval. See Cross References on page 2.)

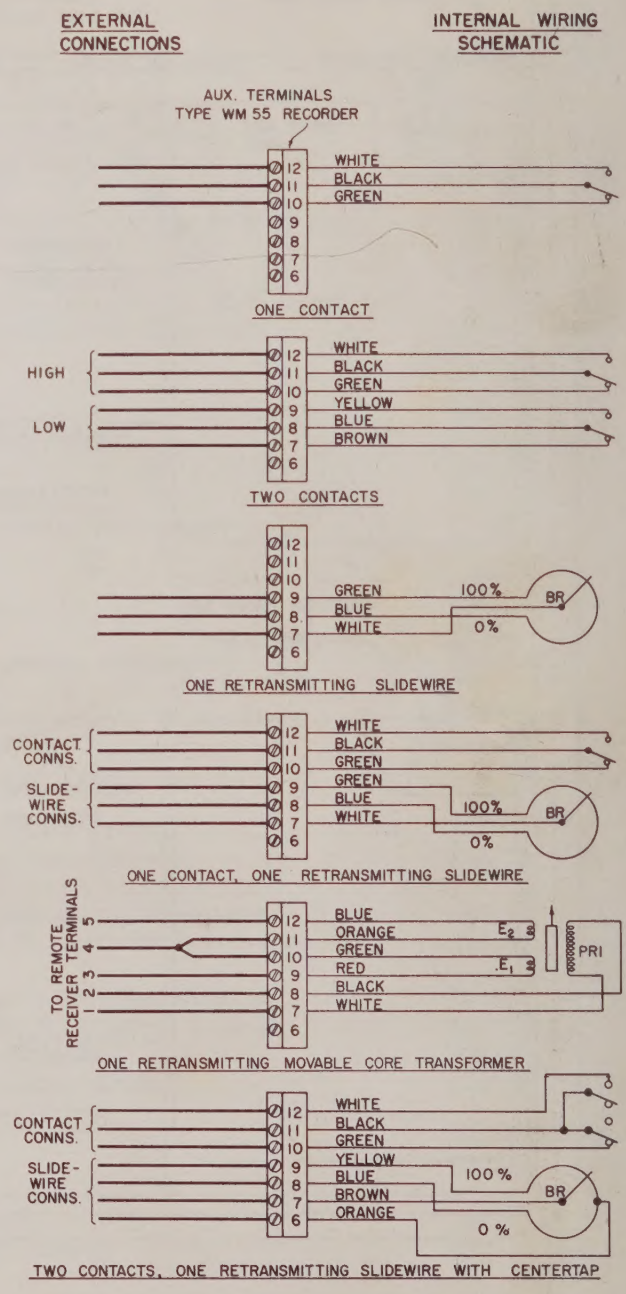


FIGURE 2 - Auxiliary Circuit External Connections (Contact Positions at 0% Chart)

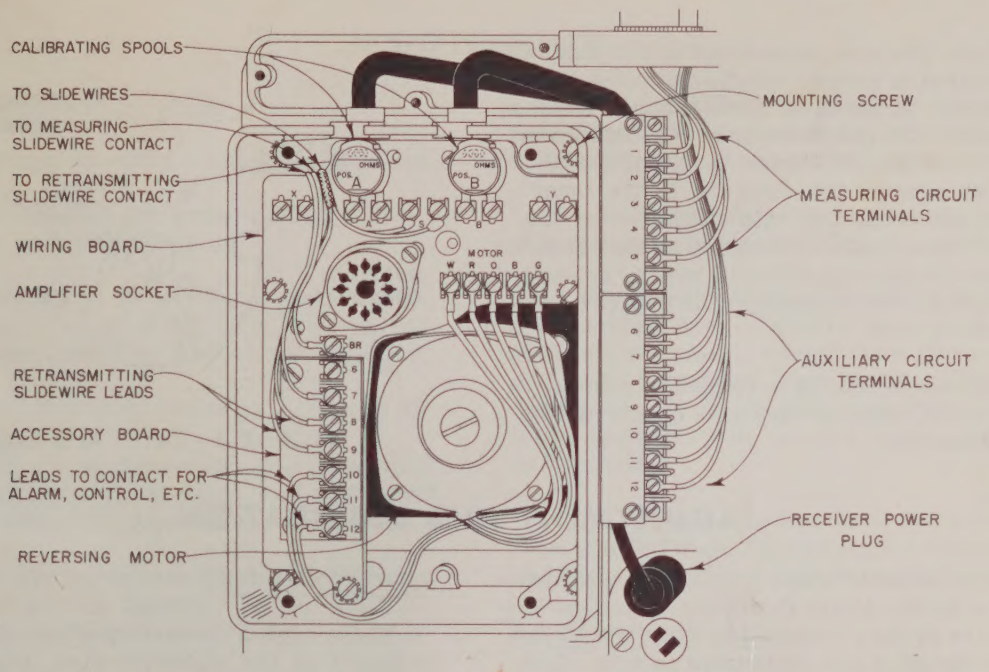


FIGURE 3 - Rear View of Electric Receiver Mounted in WM55 Recorder (Amplifier Removed)

Wiring Board

Each circuit class has a separate wiring board assembly. General component locations and connections are shown in Figure 3.

Motor Driven Slidewire Disc and Cam

The slidewire disc and cam are shown removed from the Receiver in Figure 4. The disc and cam shaft is driven by an ac induction type reversing motor with an internal gear reduction housing mounted within the Receiver. Figure 7 shows two styles of reversing motors, either of which may be mounted in any standard Receiver for the Type WM55 Recorder.

The slidewire disc is mounted on a disc hub which, in turn, is mounted on the disc and cam shaft. Shaft motion is transmitted to the disc through a spring key. Any backlash in the reduction gearing is eliminated by the backlash spring, which engages with the disc hub to put a small counterclockwise torque on the disc.

The molded slidewire disc is secured to the hub by the disc clamp whose mounting screws are accessible through the larger holes of the pen drive arm.

The desired relation between slidewire motion and recording pen travel is obtained by shaping the pen drive cam during factory

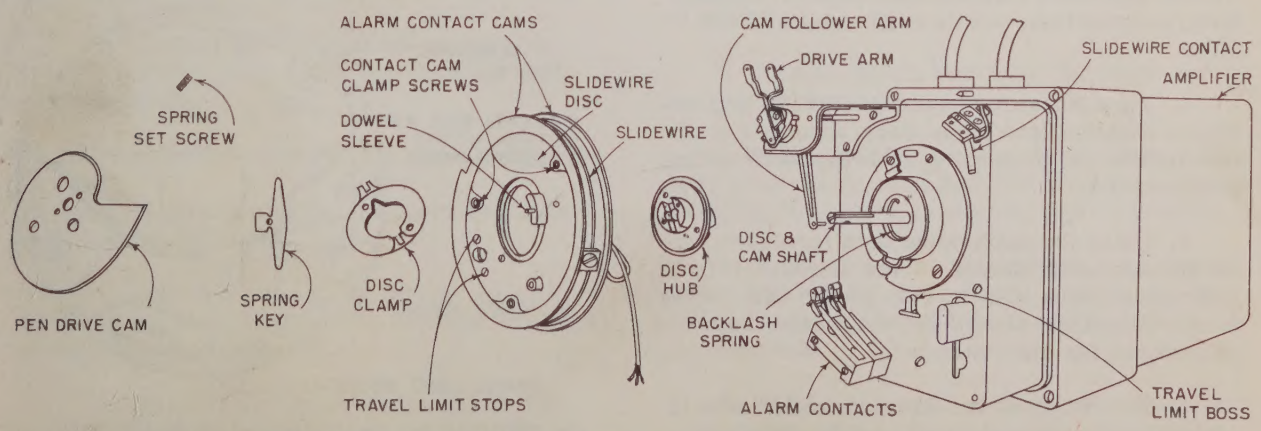


FIGURE 4 - Receiver with Slidewire Disc and Cam Removed

calibration. The cam is attached to the disc hub and is located in proper relation with the slidewire disc by means of a dowel sleeve. This cam actuates the pen drive arm. The drive arm support is shown in Figure 5. Note that the drive arm support pin must be in the lever assembly notch marked with the letter of the Recorder Case position occupied by the Receiver. To change the pin to a different notch, remove the support screw, reposition the support, and replace the screw.

The slidewire disc is arranged to support either one flat tapered slidewire or one or two round slidewires.

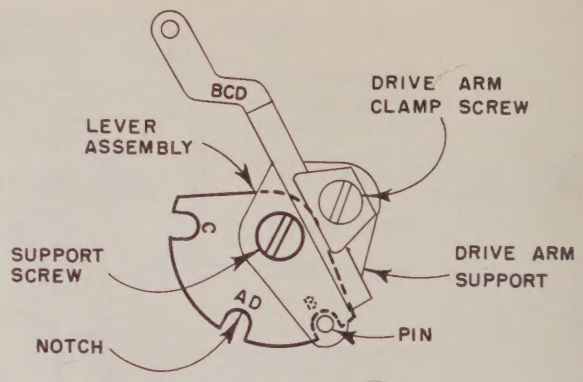


FIGURE 5 - Drive Arm Support

ADJUSTMENT AND CALIBRATION

Electric Receivers are furnished precalibrated by the Bailey Meter Company. When the Receivers are factory mounted in Type WM55 Recorders, the pens are calibrated as well. Calibration of the recording pen is necessary when the Receiver's position in the Recorder Case is changed, when a Receiver is added to a previously furnished Recorder, after parts replacement, etc.

Recording Pen Calibration (Refer to Figure 4)

1. With Recorder power switch OFF, manually rotate slidewire disc against zero travel limit stop.

2. If pen does not read zero chart, make a fine adjustment of adjustable link between Receiver drive arm and pen yoke (Figure 1), to position the pen exactly at zero. (Linkage adjustments are described under "Adjustment and Calibration" in Instruction Section E12-3.)

NOTE: For units with thermocouple or signal failure protection, pen is calibrated with 2% offset.

3. Turn Recorder power switch ON and energize transmitter. Make zero adjustment at transmitter, if necessary, to bring pen reading back to zero.

4. Using the calibration data furnished on the Specification Sheets in the front of this Instruction Book, check other points within chart range. Readings should be within the accuracy guaranteed for the instrument.

5. The length of the Receiver drive arm is set at the factory and should not be changed.

Travel Limit Stops

These stops, consisting of eccentric screws mounted on the slidewire disc, engage a boss on the Receiver case (Figure 4). They permit travel of the slidewire contact to the extremes of the wound portion of the slidewire. The zero stop is adjusted during factory calibration, and should not be changed.

Slidewire Contact

The slidewire contact should engage the slidewire lightly over its entire travel, with a pressure of 20 to 40 grams. This pressure assures proper electrical contact and minimum slidewire wear. Make certain that slidewire contact pressure is correct.

Never allow the contact to spring back onto the slidewire, for it will nick the slidewire windings, and cause rapid contact wear and premature failure.

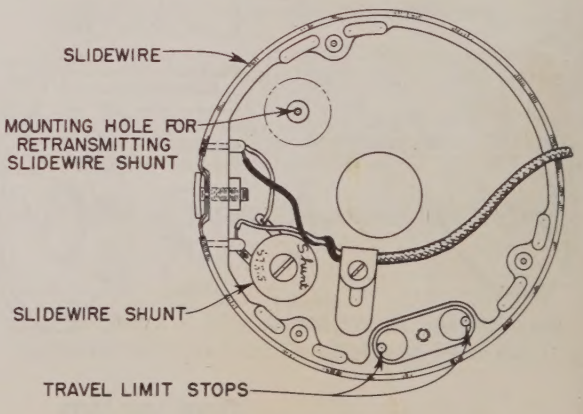


FIGURE 6 - Rear View of Slidewire Disc

MAINTENANCE

Receiver Disassembly

1. Removing Receiver from Recorder Case

a. Disconnect adjustable link from Receiver drive arm (Figure 1).

b. On back of Recorder, remove (1) the central wiring channel cover and (2) the wiring cover plate that is directly above the Receiver.

c. Pull Receiver power plug (Figure 3).

d. Remove numbered designation strip(s) from Receiver terminal block(s), and disconnect leads to the Receiver from the terminal block.

e. Remove terminal block(s) from their support, to free the fanning strip(s), which should be left on the Receiver leads.

f. Remove amplifier cover from rear of Receiver and loosen the four retained Receiver mounting screws (Figure 3).

g. Carefully withdraw Receiver from the Recorder Case, tipping slightly so that Receiver drive arm will not strike the Case.

2. Removing Motor from Receiver

a. Pull Receiver power plug (Figure 3).

b. Turn slidewire disc until it hits 100% travel limit stop (follower at low point of cam).

c. Loosen four amplifier mounting screws and carefully unplug amplifier from wiring board.

d. Remove four (or five) motor leads from wiring board (Figure 3).

e. Loosen three retained screws on motor mounting plate, and remove motor with mounting plate.

3. Removing Slidewire Disc (see Figure 4)

a. Rotate slidewire disc counterclockwise against the stop.

b. Remove cam(s) by taking out cam mounting screws (dowel sleeve remains attached to the slidewire disc).

c. Remove set screw from end of disc and cam shaft, and take out spring key (tension exerted on disc hub by backlash spring should turn disc and hub assembly counterclockwise against stop as soon as spring key is removed).

d. Take out two screws securing disc clamp to hub, and remove disc from disc hub.

e. Turn disc hub counterclockwise until all backlash spring tension is removed. Slip disc hub off shaft, taking care that backlash spring is not pulled with it. (Backlash spring should be left in its mounting unless absolutely necessary to remove it for inspection or renewal.)

f. Do not attempt to remove slidewire from molded disc. Always handle this assembly with care, in order not to damage the windings.

Receiver Reassembly

Replace slidewire disc as follows (see Figure 4):

1. Place disc hub on shaft so that one of its rear notches engages backlash spring.

2. Wind slidewire lead wires counterclockwise around narrow part of hub for two turns, and place disc on the hub. (When positioning disc, hold slidewire contact away from slidewire, and then carefully let it down on the wire.)

3. Place disc clamp in position and insert disc clamp screws. Turn screws only partway into the disc hub, so that disc can still be turned with respect to the hub.

4. Rotate disc and hub one complete turn, from zero to maximum travel limit stop, to check that slidewire leads allow full, free travel of disc.

5. Fasten spring key in position with spring key set screw.

6. While holding the disc motionless, rotate key, disc clamp, and disc hub two turns clockwise, to set proper tension on backlash spring.

7. Tighten disc clamp screws just enough to keep backlash spring from unwinding, yet still allowing disc to be turned with respect to the disc hub.

8. Rotate disc with respect to hub so that position of dowel sleeve (on the disc) with

respect to cam screw holes (on the hub) approximately corresponds to positions of the dowel and cam screw holes on the pen drive arm (look at etched side of cam).

9. Place pen drive cam in position and install two cam screws.

10. Tighten disc clamp screws (accessible through holes in the cam).

11. Manually, rotate slidewire disc and check contact position on slidewire, action of backlash spring, motion of follower on pen drive cam, and operation of the travel limit stops.

To replace the motor in the Receiver, and to remount the Receiver in the Recorder Case, follow disassembly instructions in reverse order. When positioning motor in the Receiver, be sure pinion gear engages drive gear properly. Do not force fit. The two dowels on inside of Receiver case should fit snugly into dowel holes on motor mounting plate before the three mounting screws are tightened.

After Receiver has been mounted in Recorder Case, check reading of recording pen when slidewire is against its minimum stop.

Slidewire

Maintenance of slidewire is limited to removal and replacement. If slidewire or contact becomes dirty wipe assembly with clean cloth.

Motors

If the action of the motor becomes sticky, as indicated by a stepping chart record, some exercising of the motor is recommended. This should always be done after new oil has been added to the gearbox. For Receiver applications where the measured variable changes slowly or not at all over long periods of time, the motor should be exercised through full range in both directions about once each week. This may be done by turning off the Recorder or Indicator power supply and turning the slidewire by hand.

Failure of the motor to respond to a change in variable may be from causes other than frozen motor bearings. Failure of the amplifier or some other part of the circuit may be the reason for lack of response. Electrical power to the motor is indicated on an unbalance of measuring circuit by voltage across the motor capacitor (read at the motor test jacks on the Amplifier Unit by means of an ac voltmeter). The circuit can be unbalanced in the case of Class Q resistance thermometer circuits by shorting or opening the measuring element at the Receiver terminal board, and, in a similar manner on other applications. A large unbalance of this type will produce a voltage of around 90 to 150 volts between these terminals, and will indicate that electrical torque is being developed. If the motor does not respond, the bearings obviously are frozen, and the following procedure should be followed to restore operation.

NOTE: The following procedure does not apply to oil sealed motors. If bearings are frozen in oil sealed motors, the entire motor assembly must be replaced.

If the motor is completely stuck or frozen and will not break loose, proceed as follows:

1. Remove motor assembly from Receiver case as outlined under "Receiver Disassembly".

2. Remove four screws from motor assembly. (Drive pinion need not be removed on Holtzer-Cabot motors. Allow motor mounting plate to hang loose on shaft. Bodine motors only: Drive out groov pin holding pinion gear to shaft and remove pinion gear. See Figure 7.)

3. Break seals between gearcase, motor proper, and bearing plates by placing a knife blade in external grooves and striking blade lightly with a mallet.

4. Break seal at A, Figure 7, to remove gearcase. (In Bodine motors, then remove inner plate from gearcase.)

5. Clean all residual oil out of gearcase by flushing with kerosene.

6. Break seals at B and C, Figure 7, to remove rotor and bearings. (If rear bearing cannot readily be removed from Holtzer-Cabot motors, loosen setscrew that bears on rotor endplay adjustment screw, remove rotor endplay adjustment screw and, if necessary, drive bearing out of bearing plate with a large diameter wooden dowel.)

7. Clean all residual grease from bearings with naptha. Repack bearings with Beacon 325 grease (available from the Bailey Meter Company in 2-oz. containers, Part No. 199113A1). Use just enough grease to fill wells in bearings.

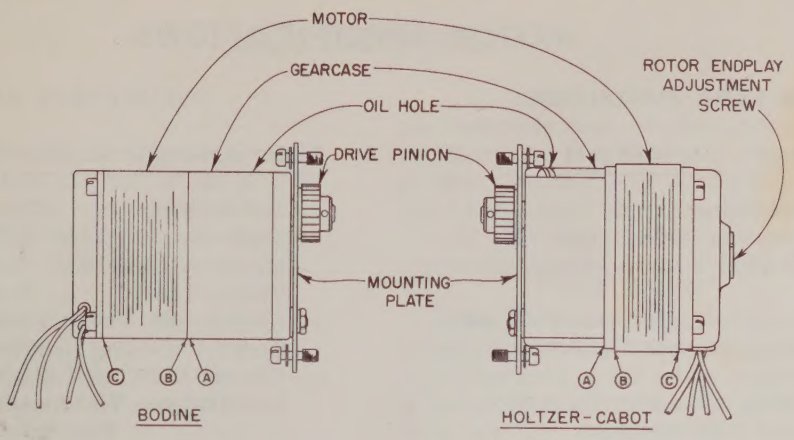


FIGURE 7 - Interchangeable Reversing Motors, Pt. No. 666329-1

Bodine motors only: Place 1 to 1-1/2 teaspoons of Lubriplate 907 grease in gear case.

8. Reassemble motor. Do not force any parts into place; they should fit together easily. Tighten four screws evenly to prevent gears from binding.

9. Lubricate motor as described under "Motor Lubrication".

10. Bench test motor, as shown in Figure 8. (In Holtzer- Cabot motors, if rotor end play adjustment screw was removed, reset its position by running motor and turning screw in until motor stalls, and then backing screw out one-half turn. Tighten setscrew.) Starting voltages are shown in Figure 8. Also check motor operation in opposite direction, by reversing connections to red and white leads. If time permits, operate motor for about 24 hours and check for excessive noise and/or erratic operation.

11. Replace motor in Receiver case as outlined under "Receiver Reassembly".

Motor Lubrication

The special lubricants used in these motors are suitable for ambient temperatures of not more than 120F.

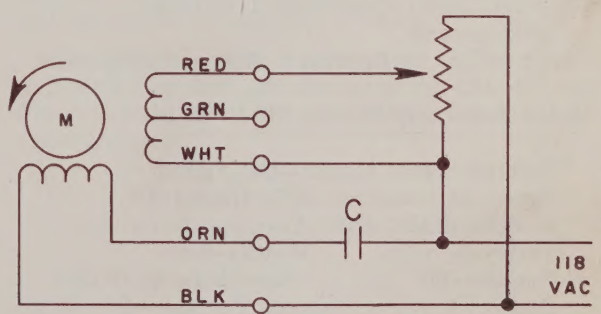
Oil-Sealed Motors - Oil sealed motors require no lubrication, but should be exercised by hand prior to placing in service to assure freedom of movement.

STANDARD MOTORS - HOLTZER-CABOT MOTORS MUST BE FILLED WITH LUBRICANT PRIOR TO PLACING IN SERVICE. These motors are emptied of lubricant prior to shipment, and must be refilled. Special lubricant and container is included for this purpose ("LUBSAC", Pt. No. 199287-1). To lubricate Holtzer-Cabot motor remove screws from oil fill hole and overflow hole (Figure 7), insert plastic tube on Lubsac into filler hole and squeeze lubricant from Lubsac. Fill until lubricant runs out of overflow hole.

BODINE MOTORS are shipped full of lubricant sufficient for 3 months operation. To lubricate Bodine motors, remove yellow screw from oil fill hole and insert 20 drops of oil. Replace screw, exercise motor by hand, and place in service.

NOTE: Lubricate both Bodine and Holtzer-Cabot motors every three months.

Lubrication requirements for each motor assembly are given under "Motor Specifications" on page 10.



Pt. No.	C Value	V = Voltage Reqd. to Start Holtzer-Cabot	Bodine
666329-1	0.75 mfd	12V	18V
6611136-1	0.75 mfd	1.0V	--
6611390-1	0.75 mfd	12V	--
6610548-1	0.75 mfd	1.0V	--
6618667-1	0.60 mfd	2.0V	2.0V
6615174-1	0.75 mfd	12V	--

FIGURE 8 - Bench Test Connections

MOTOR SPECIFICATIONS

TUBE TYPE AMPLIFIERS

Motor Assembly Pt. No. 666329-1

Holtzer-Cabot Motor
Type--ac induction RPM Output--20
Model--RBC-2405 Torque--40 oz. in.
Volts--115 Watts--9
Cycles--60 Capacitor--0.75 mfd
Control Winding Balance Voltage--20-40 volts ac
Control Winding Unbalance Voltage (Running)--110-130 volts ac
*Power Winding Voltage--185-200 volts ac
Winding Resistance at 75F--
Control: 800 ohms
Power: 800 ohms
△Lubrication--Gearcase: Sohilift P48 oil
Bearings: Beacon 325 grease

Bodine Motor
Type--ac induction RPM Output--20
Model--KLI-24RM or 21.7
Volts--115 Torque--46.5 oz. in.
Cycles--60 Watts--9.5
Capacitor--0.75 mfd
Control Winding Balance Voltage--25-45 volts ac
Control Winding Unbalance Voltage--(Running)--150-170 volts ac
*Power Winding Voltage--195-210 volts ac
Winding Resistance at 75F--
Control: 580 ohms
Power: 580 ohms
Lubrication--Gearcase: Lubriplate 907 grease
Bearings: Beacon 325 grease

Motor Assembly Pt. No. 6611390-1

Holtzer-Cabot Motor--Oil Filled
Type--ac induction RPM Output-20
Model--ROBC-2405 Torque--20 oz. in.
Volts--115 Watts--9
Cycles--60 Capacitor--0.75 mfd
Control Winding Balance Voltage--20-40Vac
Control Winding Unbalance Voltage (Running)--110-130 volts ac
*Power Winding Voltage--185-200 volts ac
Lubrication-None Required

SOLID-STATE AMPLIFIERS

Motor Assembly Pt. No. 6618667-1

Bodine Motor
Type--ac induction RPM Output-18
Model--KLI-24RM Torque--50 oz. in.
Volts--118 Watts--9
Cycles--60 Capacitor--0.6 mfd
Control Winding Unbalance Voltage--20Vac
*Power Winding Voltage--185-200 volts ac
Lubrication--Gearcase: Sohilift P48 oil
Bearings: Beacon 325 grease

Holtzer-Cabot Motor
Type--ac induction RPM Output--20
Model--RBC-2405 Torque--50 oz. in.
Volts--118 Watts--9
Cycles--60 Capacitor--0.6 mfd
Control Winding Unbalance Voltage--20Vac
*Power Winding Voltage--185-200 volts ac
△Lubrication--Gearcase: Sohilift P48 oil
Bearings: Beacon 325 grease

Motor Assembly Pt. No. 6611136-1

Holtzer-Cabot Motor
Type--ac induction RPM Output--20
Model--RBC-2405 Torque--20 oz. in.
Volts--115 Watts--9
Cycles--60 Capacitor--0.75 mfd
Control Winding Unbalance Voltage (Running)--10 volts ac
*Power Winding Voltage-185-200 volts ac
△Lubrication--Gearcase: Sohilift P48 oil
Bearings: Beacon 325 grease

Motor Assembly Pt. No. 6610548-1

Holtzer-Cabot Motor--Oil Filled
Type--ac induction RPM Output-20
Model--ROBC-2405 Torque--20 oz. in.
Volts--115 Watts--9
Cycles--60 Capacitor--0.75 mfd
Control Winding Unbalance Voltage (Running)--10 volts ac
*Power Winding Voltage--185-200 volts ac
Lubrication--None Required

△Add lubricant to motor before startup

*Can be read at motor terminals on wiring board when motor is run with amplifier removed. This arrangement requires that an eleven lead (Pt. No. 666755-1) or twelve lead (Pt. No. 666755-2) cable be connected between the amplifier plug and the socket on the wiring board.

ACCESSORIES

Alarm Contacts

When high or low limit alarm contacts are furnished with the Receiver, one or two alarm contact cams are attached to the rims of the slidewire disc. Cams and contacts are shown in Figure 4.

Factory settings are as follows:

One contact furnished: 50% of full chart.
Two contacts furnished: 25% and 75% of full chart.

To change factory settings:

1. Turn Recorder power switch OFF.

2. Check calibration of recording pen as outlined under "Adjustment and Calibration".

3. Set rear contact cam:

a. Loosen hex nut on front of slidewire disc until rear cam can be rotated. (Do not loosen two screws holding front cam.)

b. Rotate slidewire disc until recording pen indicates desired alarmpoint. While holding slidewire disc in place, rotate alarm contact cam on disc to contact-operating position and retighten hex nut to lock rear cam in place.

4. If two contacts are furnished, set front alarm contact as follows:

a. Loosen two contact cam clamping screws on front of slidewire disc until front cam can be rotated. (Do not loosen hex nut which clamps rear cam.)

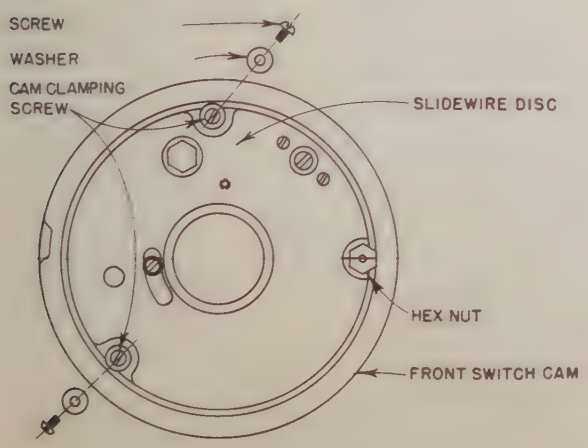


FIGURE 9 - Front View of Slidewire Disc

b. Rotate slidewire disc until recording pen indicates desired alarmpoint. While holding slidewire disc in place, rotate front cam on disc to contact-operating position. Retighten two contact cam clamping screws.

Retransmitting Slidewire

When the Receiver is equipped with two round slidewires, the slidewire closer to the pen drive arm is the retransmitting slidewire. Adjustment procedures are the same as those given for the measuring slidewire.

Retransmitting Movable Core Transformer

Figure 10 shows a Receiver equipped with a retransmitting movable core transformer. The core is positioned by a follower arm that rides on the core cam mounted in front of the pen drive cam.

This arrangement also is used in Class B circuits, where the Receiver measuring element is a movable core transformer rather than a slidewire. However, the transformer functions as a part of the measuring circuit rather than as a retransmitter, and there is no measuring slidewire on the slidewire disc.

An eccentric (see Figure 10) is provided to zero the coil position. The coil can be shifted a total of 1/8-inch along its axis. To make the adjustment, loosen the coil support screws (Allen heads), turn the eccentric until coil output is at the required value for the pen reading, and retighten the support screws.

The movable core transformer is described in Instruction Sections covering the Class J and Class B Telemeter Receivers (see Cross References).

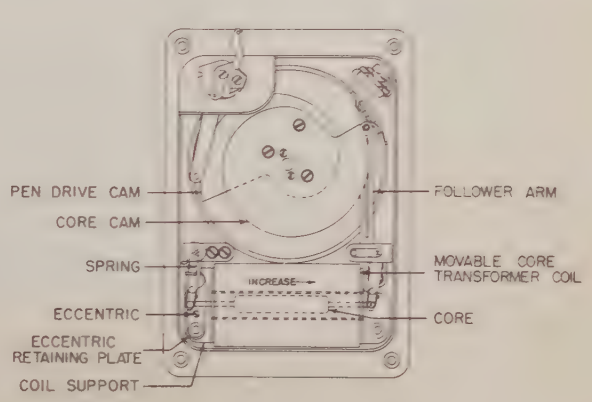


FIGURE 10 - Receiver with Retransmitting Movable Core Transformer

REPLACEMENT PARTS

Parts Drawing E12-105 (Figure 11) shows parts that are common to Electric Receivers of all circuit classes. Figure 12 is a parts drawing of the motor assemblies used in the Receivers. Refer to Instruction Sections on specific circuits for additional parts drawings that apply to each class of Receiver (See "Cross References").

Although Figures 11 and 12 normally will apply to the Receivers furnished, there may be individual differences in basic Receiver assemblies because of:

a. Design changes made since the printing of this Instruction Section.

b. Special design of the Receiver furnished to make it suitable for a non-standard application.

Therefore, when ordering parts, assure correct replacements by specifying on the order:

1. Complete Class identification and code number of the Receiver for which parts are desired. The code number is shown on a label below the Receiver nameplate.

2. The Parts Drawing on which each part is illustrated. (The Parts Drawing Number is given in the title for Figure.)

Parts Drawings for Recorders, including pen assemblies, are shown in Instruction Section E12-3, Type KM55 or WM55 Recorder and KM53 or WM53 Indicator.

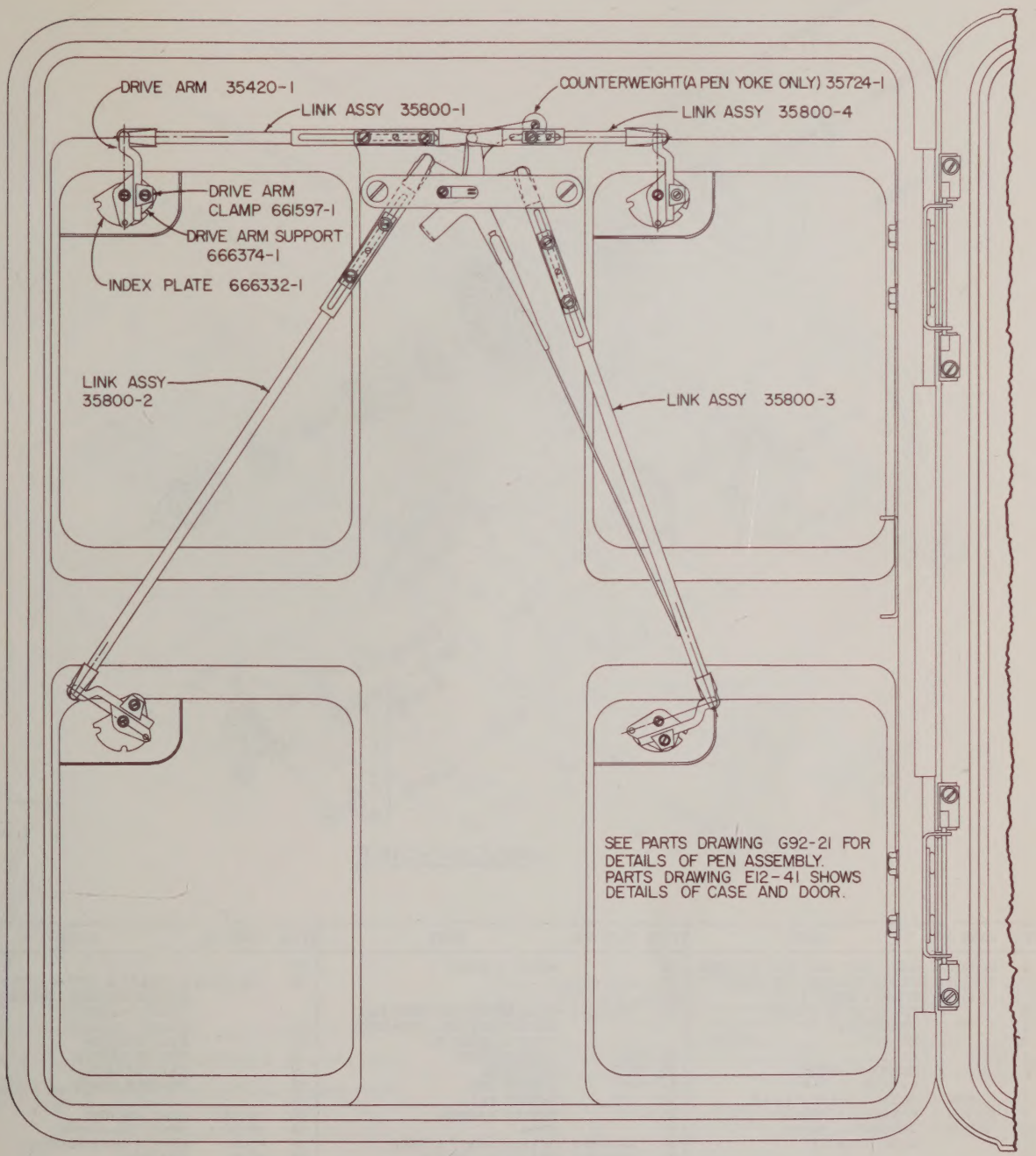
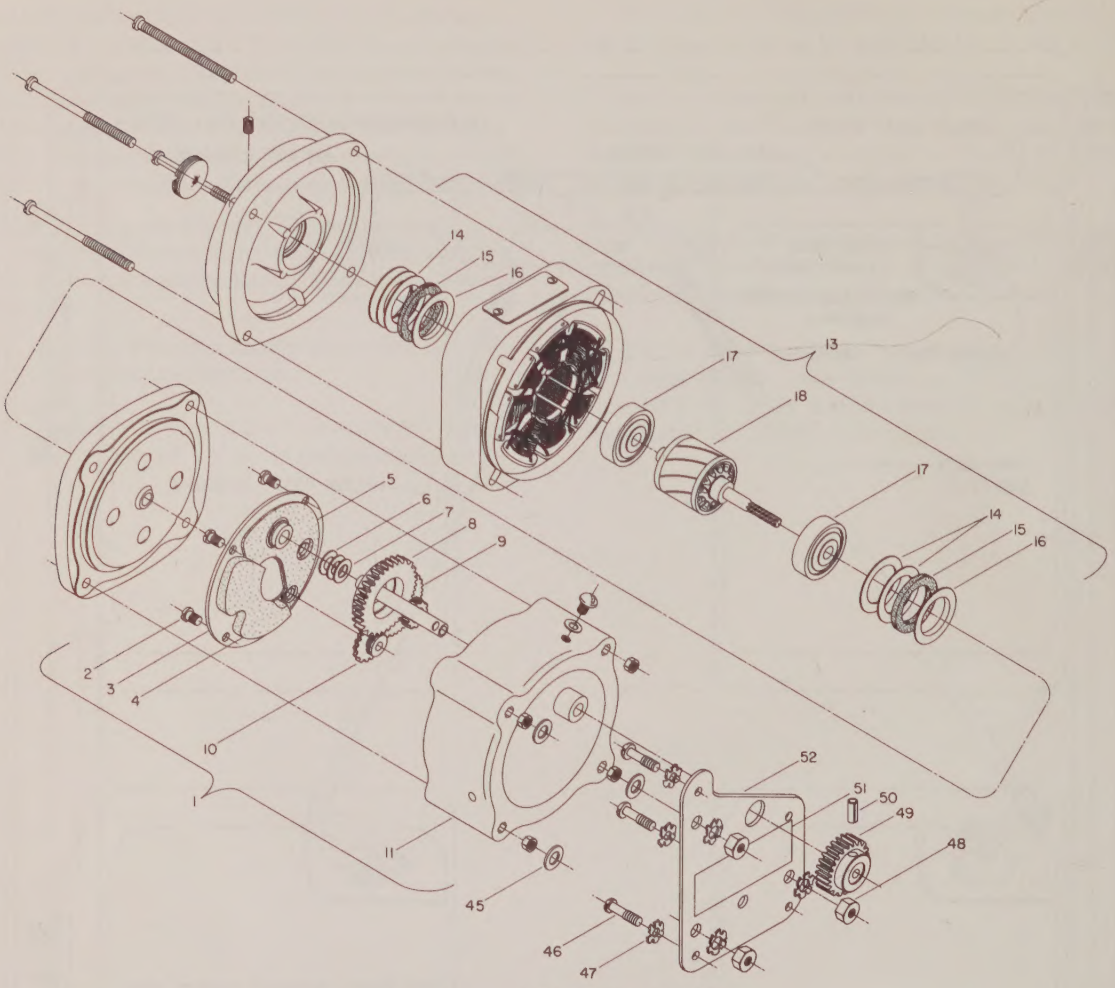

DRIVE ARM 35420-1
LINK ASSY 35800-1
COUNTERWEIGHT(A PEN YOKE ONLY) 35724-1
LINK ASSY 35800-4
DRIVE ARM CLAMP 661597-1
DRIVE ARM SUPPORT 666374-1
INDEX PLATE 666332-1
LINK ASSY 35800-2
LINK ASSY 35800-3
SEE PARTS DRAWING G92-21 FOR DETAILS OF PEN ASSEMBLY.
PARTS DRAWING E12-41 SHOWS DETAILS OF CASE AND DOOR.

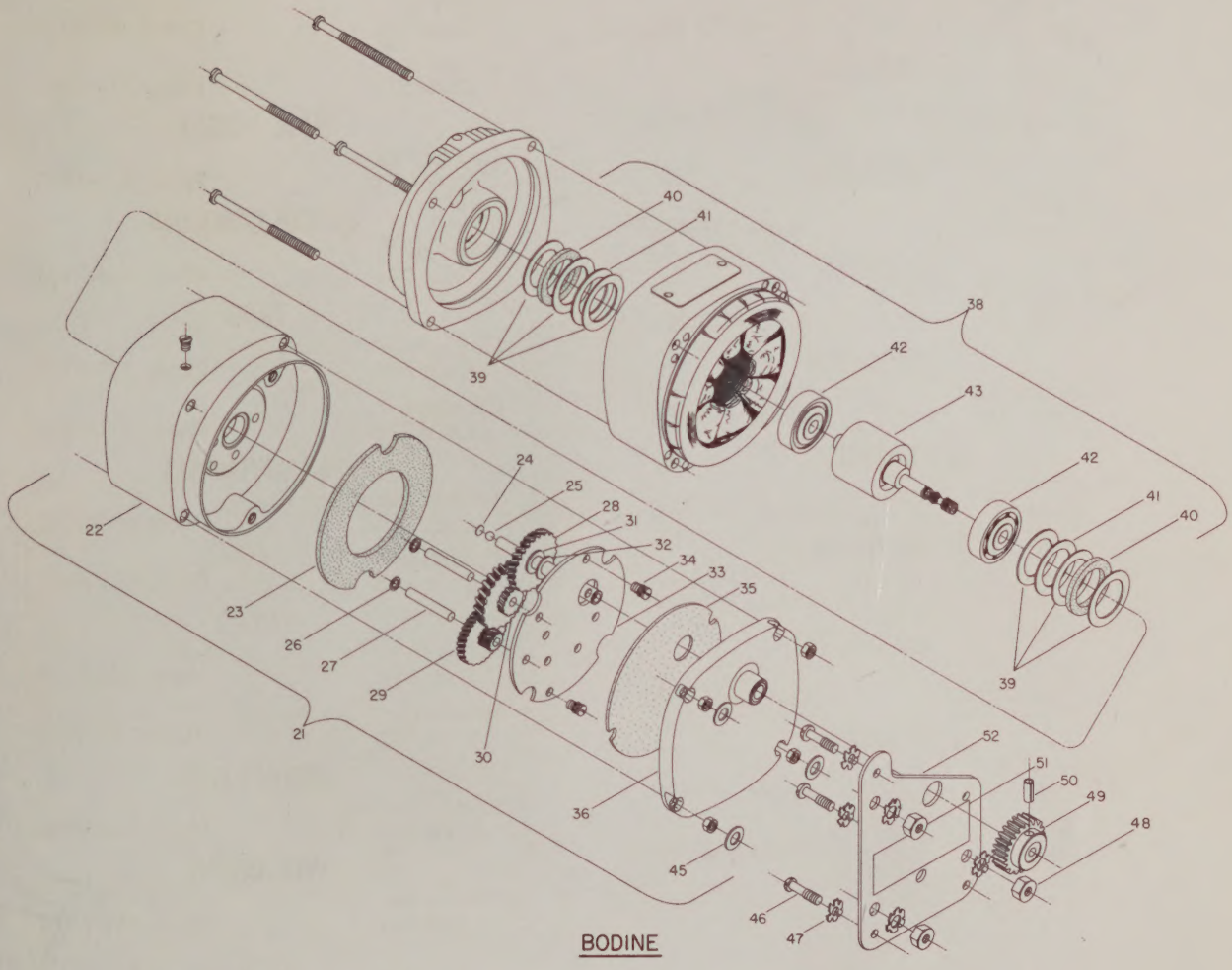
FIGURE 11 - Parts Drawing E12-105, Electric Receivers in Type WM55 Recorder



HOLTZER-CABOT

ITEM	PART NO.	NAME
1	1942610-1	GEAR UNIT ASSY FOR HOLTZER-CABOT MOTORS - INCLUDES ITEMS 2 THRU 11
2		TRAINPLATE SCREWS
3		TRAINPLATE
4		FELT
5		FELT
6		SPRING WASHER
7		WASHER
8	1942699-1	OUTPUT SHAFT & GEAR
9	1942698-1	2ND GEAR & PINION
10	1942697-1	1ST GEAR & PINION
11		GEAR HOUSING
12		
13	1942612-1	SHAFT & ROTOR ASSY FOR HOLTZER-CABOT MOTORS - INCLUDES ITEMS 14 THRU 18
14		END PLAY WASHER
15		CORK WASHER
16		COLLAR
17		BALL BEARING
18		ROTOR & SHAFT
19		
20		
21	1942611-1	GEAR REDUCTION UNIT FOR BODINE MOTORS - INCLUDES ITEMS 22 THRU 36
22		GEAR HOUSING
23		FELT RING
24		THRUST DISC
25		THRUST BALL
26		THRUST WASHER
27		STUD
28	1942702-1	OUTPUT SHAFT & GEAR
29	1942701-1	2ND GEAR & PINION
30	1942700-1	1ST GEAR & PINION
31		NYLON WASHER
32		PAPER WASHER
33		COVER PLATE
34		SCREW & LOCKWASHER
35		FELT DISC
36		BACK CAP
37		
38	SEE NOTE 3	SHAFT & ROTOR ASSY FOR BODINE MOTORS - INCLUDES ITEMS 39 THRU 43
39		SPACING WASHER
40		FELT WASHER
41		SPRING WASHER
42		BALL BEARING
43		ROTOR & SHAFT
44		
45	#8 SAE	FLAT WASHER
46	666719-1	MOUNTING SCREW
47	#1108	SHKPRF LOCKWASHER
48	#8-32	HEX NUT
49	666327-1	DRIVE PINION
50	3/32x3/8 LG.	ROLL PIN
51	1961038-1	INSTRUCTION PLATE
52	666318-1	MOTOR MOUNTING PLATE

FIGURE 12 - Parts Drawing E12-11



MOTOR ASSY SEE NOTE 1	MOTOR NO. SEE NOTE 2	GEAR REDUCTION UNIT ITEM 1 AND 21	SHAFT & ROTOR ITEM 13 AND 38
666329-1	1941493-1	HOLTZER-CABOT 1942610-1 BODINE 1942611-1	SEE NOTE 3
6610548-1	1943262-1	NONE	NONE
6611136-1	1942108-1	1942610-1	1942612-1
6611390-1 6615174-1	1943143-1 6611136-1	NONE	NONE
6618667-1	1944283-1	HOLTZER-CABOT 1942610-1 BODINE 1942611-1	1942612-1 1942613-2

NOTE 1: INCLUDES ITEMS 1 THRU 52 (AS APPLICABLE).

NOTE 2: INCLUDES ITEMS 1 THRU 44 ONLY (AS APPLICABLE).

NOTE 3: PART NO. 1942613-1 UP TO SERIAL NUMBER 4769300; PART NO. 1942613-2, SERIAL NO. 4905701 AND ABOVE

ITEMS FOR WHICH PART NUMBERS ARE NOT SHOWN ARE AVAILABLE AS PART OF THE APPLICABLE SUB-ASSEMBLY ONLY.

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